

### **Inverse Square Law**

Relationship between radiance (radiant intensity) and irradiance





Surface Radiance: power per unit foreshortened area emitted into a solid angle

$$L = \frac{d^2 \Phi}{dA_f d\omega}$$

(watts/m2 - steradian)



# **Pseudo-Radiance**

### Consider two definitions:

• Radiance:

power per unit foreshortened area emitted into a solid angle

• Pseudo-radiance

power per unit area emitted into a solid angle

- Why should we work with radiance rather than pseudoradiance?
  - Only reason: Radiance is more closely related to our intuitive notion of "brightness".



# Lambertian Surfaces

- A particular point P on a Lambertian (perfectly matte) surface appears to have the same brightness no matter what angle it is viewed from.
  - Piece of paper
  - Matte paint
- Doesn't depend upon incident light angle.
- What does this say about how they emit light?



Area of black box = 1 Area of orange box = 1/cos(Theta) Foreshortening rule.



# **Lambertian Surfaces**

Relative magnitude of light scattered in each direction. Proportional to cos (Theta).





Area of black box = 1 Area of orange box = 1/cos(Theta) Foreshortening rule.



#### **Computer Vision**

# The BRDF

#### The bidirectional reflectance distribution function.















#### Geometry

Goal: Relate the radiance of a surface to the irradiance in the image plane of a simple optical system.





We need to determine  $d\Phi$  and dA



Surface Irradiance:  $E = R \cos i / r^2$ 



### **Reflections from a Surface II**

Now treat small surface area as an emitter

• ....because it is bouncing light into the world

How much light gets reflected?



- E is the surface irradiance
- L is the surface radiance = luminance
- They are related through the surface reflectance function:

$$\frac{L_{s}}{E} = \rho(i,e,g,\lambda)$$

May also be a function of the wavelength of the light



 $dA_{s}d\omega$ 

Luminance of patch (known from previous step)

What is the power of the surface patch as a source in the direction of the lens?

$$d^2\Phi = L_s dA_s d\omega$$



#### **Computer Vision**

### Through a Lens Darkly



In general:

- $L_s$  is a function of the angles i and e.
- Lens can be quite large
- Hence, must integrate over the lens solid angle to get  $d\Phi$

$$d\Phi = dA_{s} \int_{\Omega} L_{s} d\Omega$$

Lens diameter is small relative to distance from patch



# **Putting it Together**

$$d\Phi = dA_{s} \int L_{s} d\Omega$$
  
= dA\_{s} cos e L\_{s}  $\frac{\pi (d/2)^{2} cos \alpha}{(z / cos \alpha)^{2}}$ 

Power concentrated in lens:

$$d\Phi = \frac{\pi}{4} L_s dA_s \left[\frac{d}{Z}\right]^2 \cos e \cos^3 \alpha$$

Assuming a lossless lens, this is also the power radiated by the lens as a source.





$$\frac{dA_{s}\cos e}{\left(Z/\cos \alpha\right)^{2}} = \frac{dA_{i}\cos \alpha}{\left(-f/\cos \alpha\right)^{2}} \qquad \qquad \frac{dA_{s}}{dA_{i}} = \frac{\cos \alpha}{\cos e} \left(\frac{Z}{-f}\right)^{2}$$

Computer Visior

# **The Fundamental Result**

Source Radiance to Image Sensor Irradiance:

$$\frac{dA_{s}}{dA_{i}} = \frac{\cos \alpha}{\cos e} \left(\frac{Z}{-f}\right)^{2}$$

$$E_i = L_s \frac{dA_s}{dA_i} \frac{\pi}{4} \left[\frac{d}{Z}\right]^2 \cos e \cos \frac{3}{\alpha}$$

$$E_{i} = L_{s} \frac{\cos \alpha}{\cos e} \left(\frac{Z}{-f}\right)^{2} \frac{\pi}{4} \left(\frac{d}{Z}\right)^{2} \cos e \cos \frac{3}{\alpha}$$

$$E_{i} = L_{s} \frac{\pi}{4} \left[\frac{d}{-f}\right]^{2} \cos^{4}\alpha$$



### **Radiometry Final Result**

$$E_{i} = L_{s} \frac{\pi}{4} \left[\frac{d}{-f}\right]^{2} \cos^{4} \alpha$$

#### Image irradiance is a function of:

- Scene radiance L<sub>s</sub>
- Focal length of lens f
- Diameter of lens d
  - f/d is often called the 'effective focal length' of the lens
- $\bullet$  Off-axis angle  $\alpha$



#### **Computer Visior**

# $\cos^4 \alpha$ Light Falloff



#### Top view shaded by height





#### Computer Vision

### **Limitation of Radiometry Model**

Surface reflection ρ can be a function of viewing and/or illumination angle



- ρ may also be a function of the wavelength of the light source
- Assumed a point source (sky, for example, is not)

Introduction to

#### Computer Visio

### Lambertian Surfaces

- The BRDF for a Lambertian surface is a constant
  - $\rho(\mathbf{i}, \mathbf{e}, \mathbf{g}, \boldsymbol{\varphi}_{\mathbf{e}} \boldsymbol{\varphi}) = \mathbf{k}$
  - function of cos e due to the foreshortening effect
  - k is the 'albedo' of the surface
  - Good model for diffuse surfaces
- Other models combine diffuse and specular components (Phong, Torrance-Sparrow, Oren-Nayar)





### BRDF

Ron Dror's thesis

### **Reflection parameters**



Figure 2.6. Grid showing range of reflectance properties used in the experiments for a particular real-world illumination map. All the spheres shown have an identical diffuse component. In Pellacini's reparameterization of the Ward model, the specular component depends on the c and d parameters. The strength of specular reflection, c, increases with  $\rho_s$ , while the sharpness of specular reflection, d, decreases with  $\alpha$ . The images were rendered in *Radiance*, using the techniques described in Appendix B.



#### Computer Vision

# **Real World Light Variation**

#### **Real World Illuminations**



(a) "Beach"



(b) "Building" (c)



(c) "Campus"



(d) "Eucalyptus"

(e) "Galileo"



(f) "Grace"



(g) "Kitchen"



(h) "St. Peter's"



(i) "Uffizi"



#### **Computer Vision**

# Fake Light and Real Light

Artificial Illuminations



(a) Point source



(b) Multiple points



(c) Extended



(d) White noise



(e) Pink noise



#### **Computer Vision**

### Simple and Complex Light



Figure 2.9. (a) A shiny sphere rendered under illumination by a point light source. (b) The same sphere rendered under photographically-acquired real-world illumination. Humans perceive reflectance properties more accurately in (b).





Figure 3.1. A viewer observes a surface patch with normal N from direction  $(\theta_r, \phi_r)$ .  $L(\theta_i, \phi_i)$  represents radiance of illumination from direction  $(\theta_i, \phi_i)$ . The coordinate system is such that N points in direction (0, 0).

$$B(\theta_r, \phi_r) = \int_{\phi_i=0}^{2\pi} \int_{\theta_i=0}^{\pi/2} L(\theta_i, \phi_i) f(\theta_i, \phi_i; \theta_r, \phi_r) \cos \theta_i \sin \theta_i \, d\theta_i \, d\phi_i,$$



#### **Computer Vision**



Figure 3.6. A photograph of a matte sphere, shown against a uniform gray background. This image could also be produced by a chrome sphere under appropriate illumination, but that scenario is highly unlikely.